













M. Sdika <sup>1</sup> V. Callot <sup>2</sup>

 $^1$ Univ.Lyon, INSA-Lyon, Université Claude Bernard Lyon 1, UJM-Saint Etienne, CNRS, Inserm, CREATIS UMR 5220, U1206, F-69100, LYON, France

<sup>2</sup>Aix Marseille Univ, CNRS, CRMBM, Marseille, France, APHM, Hôpital de la Timone, Pôle d'imagerie médicale,

CEMEREM, Marseille, France





Plan

#### Introduction

Method

Results





► Function : neural signals conduction Brain ↔ Peripheral nervous system

3/22



Spinal Cord

- $\blacktriangleright$  Function : neural signals conduction Brain  $\leftrightarrow$  Peripheral nervous system
- Can be damaged due to
  - neudegenerative desease : amyotrophic lateral sclerosis (ALS), multiple sclerosis (MS), neuromyelitis optica (NMO), etc.
  - spinal cord injuries, trauma



Spinal Cord

- $\blacktriangleright$  Function : neural signals conduction Brain  $\leftrightarrow$  Peripheral nervous system
- Can be damaged due to
  - neudegenerative desease : amyotrophic lateral sclerosis (ALS), multiple sclerosis (MS), neuromyelitis optica (NMO), etc.
  - spinal cord injuries, trauma
- Symptoms :
  - loss of sensation
  - loss of coordination
  - pain
  - paralysis



MRI based Spinal Cord Studies

Image registration : atlas based segmentation, group studies, morphometry, motion correction





### MRI based Spinal Cord Studies

- Image registration : atlas based segmentation, group studies, morphometry, motion correction
- Image segmentation : atrophy measurement, physiological parameter measurement





### MRI based Spinal Cord Studies

- Image registration : atlas based segmentation, group studies, morphometry, motion correction
- Image segmentation : atrophy measurement, physiological parameter measurement
- Centerline localization
  - Can be used as an initial step for all processing







### MRI based Spinal Cord Studies

- Image registration : atlas based segmentation, group studies, morphometry, motion correction
- Image segmentation : atrophy measurement, physiological parameter measurement
- Centerline localization
  - Can be used as an initial step for all processing
  - Nothing satisfying in the literature if we want to be
    - robust to image resolution
    - robust to pathologies
    - robust to contrast, MR scanner







Plan

Introduction

#### Method

Results





Using Machine Learning for Spinal Cord Localization

$$SCC(p) = \begin{cases} > 0 & \text{if SC} \\ < 0 & \text{otherwise} \end{cases}$$

$$f$$

$$Spinal$$

$$Cord$$

$$Classifier$$

$$f$$

$$p=patch$$



Using Machine Learning for Spinal Cord Localization



$$SCC(p) = \begin{cases} > 0 & \text{if SC} \\ < 0 & \text{otherwise} \end{cases}$$

$$f$$

$$Spinal$$

$$Cord$$

$$Classifier$$

$$f$$

$$p=patch$$





Using Machine Learning for Spinal Cord Localization





HOG feature with linear SVM classifier (Dalal & Triggs 2005)



Computing a Localization Map







Centerline Extraction

•  $c_z$  : centerline of the SC on slice z





Centerline Extraction

CREATIS

- $c_z$  : centerline of the SC on slice z
- naive :  $c_z = \operatorname{argmax}_x S_z(x)$ 
  - not robust to classifier failure (false positive)
  - does not account for centerline continuity



Centerline Extraction

- $c_z$  : centerline of the SC on slice z
- naive :  $c_z = \operatorname{argmax}_x S_z(x)$ 
  - not robust to classifier failure (false positive)
  - does not account for centerline continuity
- Proposition : solve

$$\min_{c_0,\ldots,c_{n-1}} - \sum_{z=0}^{n-1} S_z(c_z) + \lambda \sum_{z=0}^{n-2} \|c_{z+1} - c_z\|^2,$$

- local optimization (gradient descent) : fast, not robust
- global optimization : robust, very slow (brute force : exponential)



Fast Global solution of the optimization problem

Solve

$$\min_{c_0,\ldots,c_{n-1}} C_{n-1}(c_0,\ldots,c_{n-1}) = -\sum_{z=0}^{n-1} S_z(c_z) + \lambda \sum_{z=0}^{n-2} \|c_{z+1} - c_z\|^2,$$



Fast Global solution of the optimization problem

#### Solve

$$\min_{c_0,\ldots,c_{n-1}} C_{n-1}(c_0,\ldots,c_{n-1}) = -\sum_{z=0}^{n-1} S_z(c_z) + \lambda \sum_{z=0}^{n-2} \|c_{z+1} - c_z\|^2,$$

#### Define :

$$M_k(x_k) = \min_{x_0,...,x_{k-1}} C_k(x_0,...,x_{k-1}).$$



Fast Global solution of the optimization problem

#### Solve

$$\min_{c_0,\ldots,c_{n-1}} C_{n-1}(c_0,\ldots,c_{n-1}) = -\sum_{z=0}^{n-1} S_z(c_z) + \lambda \sum_{z=0}^{n-2} \|c_{z+1} - c_z\|^2,$$

#### Define :

$$M_k(x_k) = \min_{x_0,\ldots,x_{k-1}} C_k(x_0,\ldots,x_{k-1}).$$

Solution on the last slice :

$$\min_{x_{n-1}} M_{n-1}(x_{n-1}) = \min_{x_0, \dots, x_{n-1}} C_{n-1}(x_0, \dots, x_{n-1})$$





Fast Computation of the  $M_k$  sequence

Distance/NN transform for greylevel image (Meijster 2002, Felzenszwalb 2012) :

$$D(f)(x) = \min_{y} f(y) + ||x - y||^2$$

$$N(f)(x) = \operatorname*{argmin}_{y} f(y) + \|x - y\|^2$$





Fast Computation of the  $M_k$  sequence

Distance/NN transform for greylevel image (Meijster 2002, Felzenszwalb 2012) :

$$D(f)(x) = \min_{y} f(y) + \|x - y\|^{2} \qquad N(f)(x) = \operatorname*{argmin}_{y} f(y) + \|x - y\|^{2}$$

$$M_{k}(x_{k}) = -S_{k}(x_{k}) + \lambda \min_{x_{k-1}} \left\{ \frac{M_{k-1}(x_{k-1})}{\lambda} + \|x_{k} - x_{k-1}\|^{2} \right\}$$
  
=  $-S_{k}(x_{k}) + \lambda D\left(\frac{M_{k-1}}{\lambda}\right)(x_{k})$ 



Fast Computation of the  $c_k$  path

$$M_k(c_k) = -S_k(c_k) + \lambda D\left(rac{M_{k-1}}{\lambda}
ight)(c_k)$$



Fast Computation of the  $c_k$  path

$$\begin{array}{ll} \mathcal{M}_k(c_k) &=& -S_k(c_k) + \lambda D\left(\frac{\mathcal{M}_{k-1}}{\lambda}\right)(c_k) \\ &=& -S_k(c_k) + \lambda \min_{x_{k-1}} \left\{\frac{\mathcal{M}_{k-1}(x_{k-1})}{\lambda} + \|c_k - x_{k-1}\|^2\right\} \end{array}$$



Fast Computation of the  $c_k$  path

$$\begin{aligned} M_k(c_k) &= -S_k(c_k) + \lambda D\left(\frac{M_{k-1}}{\lambda}\right)(c_k) \\ &= -S_k(c_k) + \lambda \min_{x_{k-1}} \left\{\frac{M_{k-1}(x_{k-1})}{\lambda} + \|c_k - x_{k-1}\|^2\right\} \end{aligned}$$

If  $c_k$  is known, then  $c_{k-1}$  is given by

$$c_{k-1} = \operatorname{argmin}_{x_{k-1}} \frac{M_{k-1}(x_{k-1})}{\lambda} + \|c_k - x_{k-1}\|^2$$
$$= N\left(\frac{M_{k-1}}{\lambda}\right)(c_k)$$



Fast Centerline Extraction Algorithm : linear complexity

#### Algorithm 1 Center Line Extraction Procedure

1: procedure ExtractCenterLine(S,  $\lambda$ ) 2:  $M_0 = -S_0$ 3: for z=1 :n-1 do 4:  $M_z = -S_z + \lambda D\left(\frac{M_{z-1}}{\lambda}\right)$ 5:  $N_z = N\left(\frac{M_{z-1}}{\lambda}\right)$ 6:  $c_{n-1} = \operatorname{argmin}_x M_{n-1}(x)$ 7: for z=n-2 :0 do 8:  $c_z = N_{z+1}(c_{z+1})$ 













S





















Plan

Introduction

Method

Results



Dataset

- 3D  $T_1$  MRI acquired at the CRMBM (Marseille)
- ▶ 8 images from healthy control subject
- ▶ 8 images from subject with pathology (MS, compression)
- voxel size :  $1mm \times 1mm \times 1mm$
- matrix :  $176 \times 264 \times 384$





Computation time

Localization map		Global Optimization
1 Core	8 Cores	
17	2	0.4

CPU time in second



# Visual Examples : Comparison with sct-propseg (De Leener 2014)



save me





Results

Evaluation Criterion : detected centerline inside/outside the true spinal cord Results reported for slices with spinal cord only.





Results

Evaluation Criterion : detected centerline inside/outside the true spinal cord Results reported for slices with spinal cord only.

	sct-propseg	Classifier Only	Regul + Glob. Opti
		$\lambda = 0$	$\lambda = 1$
Controls	25± 32	$30 \pm 17$	$0.8 \pm 1$
Patients	$55\pm45$	$25 \pm 07$	3.0 ±4

Error percentage : mean/std-dev percent of slices with the centerline outside the true spinal cord





Brain Vs Spine Separation : Preliminary Results





Plan

Introduction

Method

Results



- ▶ Robust and efficient method for the extraction of the spinal cord extraction
  - Robust : Combination of machine learning and **global** optimization
  - Fast : Linear time complexity algorithm for the global optimization



- Robust and efficient method for the extraction of the spinal cord extraction
  - Robust : Combination of machine learning and **global** optimization
  - Fast : Linear time complexity algorithm for the global optimization
- Brain vs Spinal cord separation



- Robust and efficient method for the extraction of the spinal cord extraction
  - Robust : Combination of machine learning and **global** optimization
  - Fast : Linear time complexity algorithm for the global optimization
- Brain vs Spinal cord separation
- Ongoing Work : Large Scale evaluation (with NeuroPoly, Polytechnic Montréal)
  - about 500 subjects
  - Multiple MRI contrast  $(T_1, T_2, T_2^*, DWI)$
  - Multiple imaging center
  - large variety of image resolution
  - large variety of pathology (MS, ALS, trauma,...)



- Robust and efficient method for the extraction of the spinal cord extraction
  - Robust : Combination of machine learning and **global** optimization
  - Fast : Linear time complexity algorithm for the global optimization
- Brain vs Spinal cord separation
- Ongoing Work : Large Scale evaluation (with NeuroPoly, Polytechnic Montréal)
  - about 500 subjects
  - Multiple MRI contrast  $(T_1, T_2, T_2^*, DWI)$
  - Multiple imaging center
  - large variety of image resolution
  - large variety of pathology (MS, ALS, trauma,...)
- ► Soon freely available for academic (CREATIS website + Spinal Cord Toolbox)





Acknowledgments

Funded by :

- FLi France Life Imaging (WP4), "Agence Nationale pour la Recherche", programme "investissements d'avenir : ANR-11-INBS-0006.
- PRIMES the LABEX PRIMES (ANR-11-LABX-0063) of Université de Lyon, within the program "Investissements d'Avenir" (ANR-11-IDEX-0007) operated by the French National Research Agency (ANR).



Thanks for your attention !!