

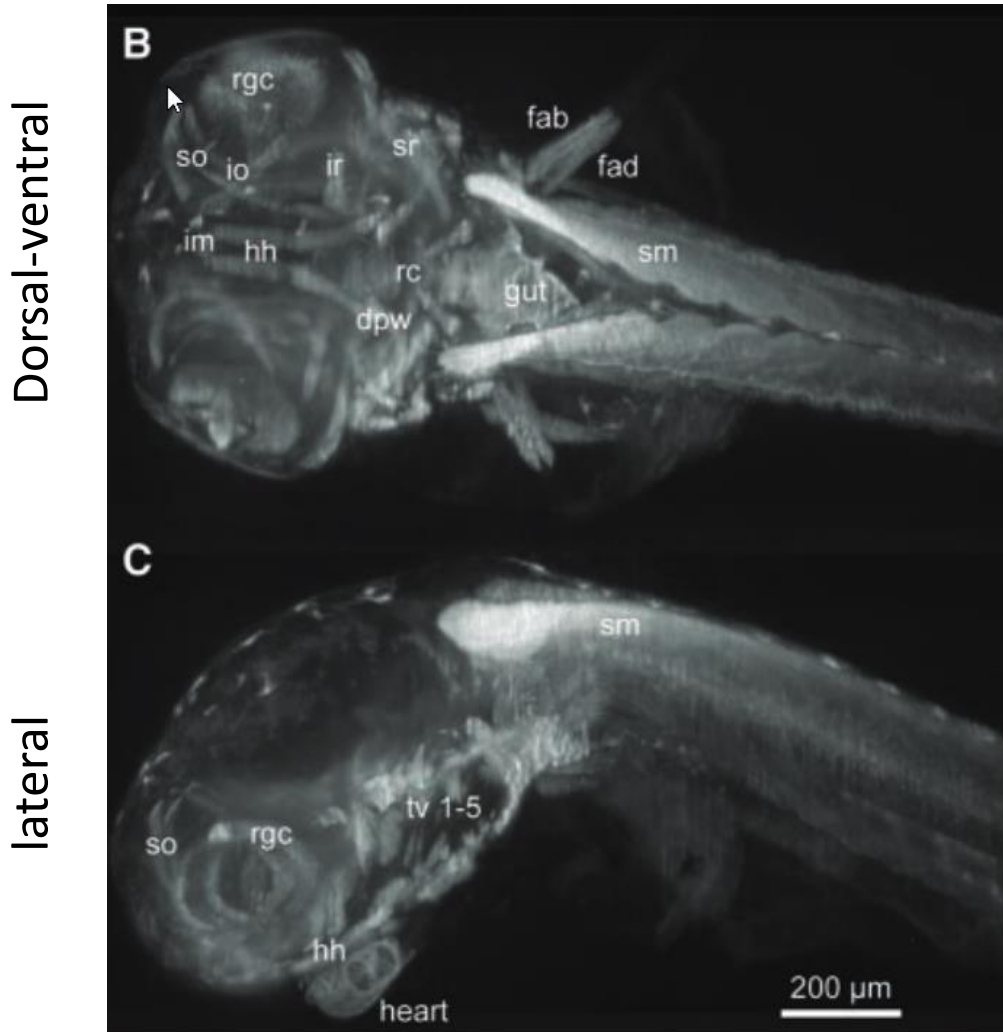
LSFM hyperspectrale structurée pour l'imagerie quantitative

S Crombez¹, C Exbrayat-Heritier¹, F Ruggiero¹, C Ray¹, Nicolas
Ducros^{1,3}

¹CREATIS, Univ Lyon, INSA-Lyon, UCB Lyon 1, CNRS, Inserm, Lyon, France

²IGFL, ENS Lyon, France

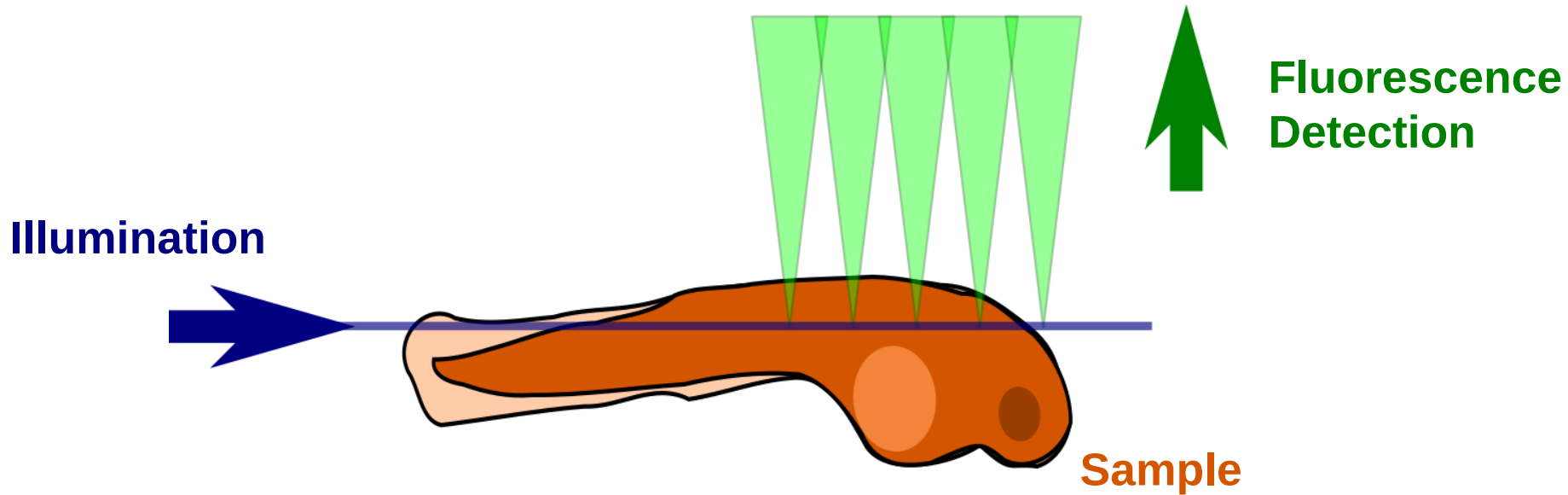
³IUF, Institut Universitaire de France



- ✓ Fluorescence samples
- ✓ GFP-labeled transgenic embryos
- ✓ Developmental study

- ✓ Wide field ($\sim\text{mm}^3$),
- ✓ High res ($\sim\mu\text{m}$)
- ✓ Fast (10 fps)

[J Huisken *et al*,
Science, **305**, (2004)]



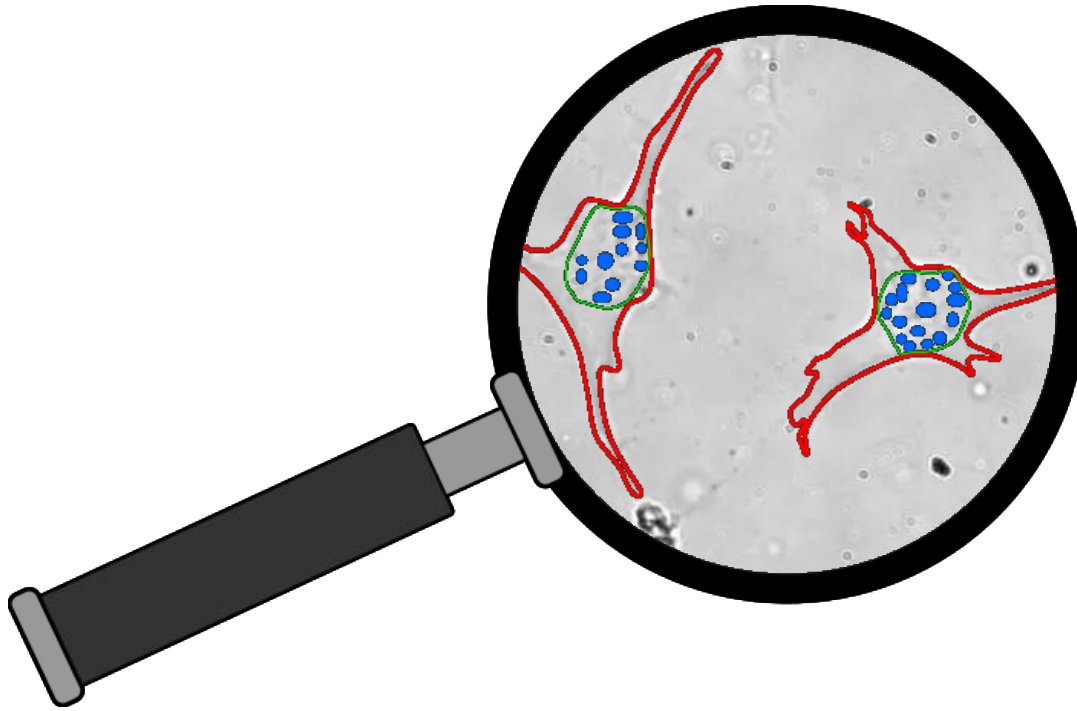
- ✓ Optical sectioning as deep as 500 μm

Compared to confocal

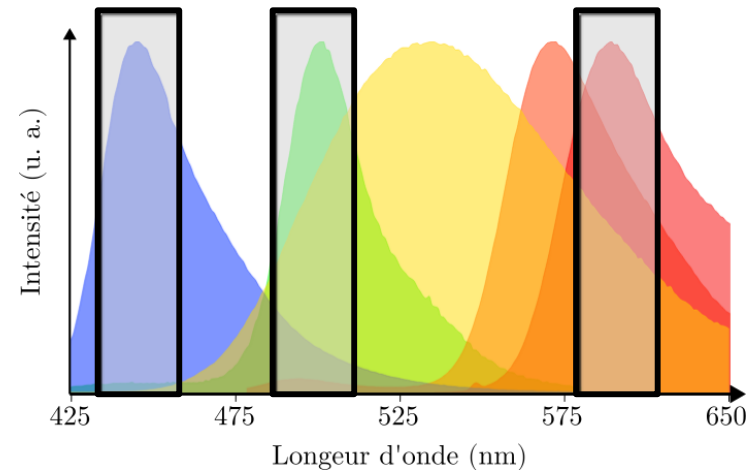
- ✓ Low photobleaching
- ✓ Fast

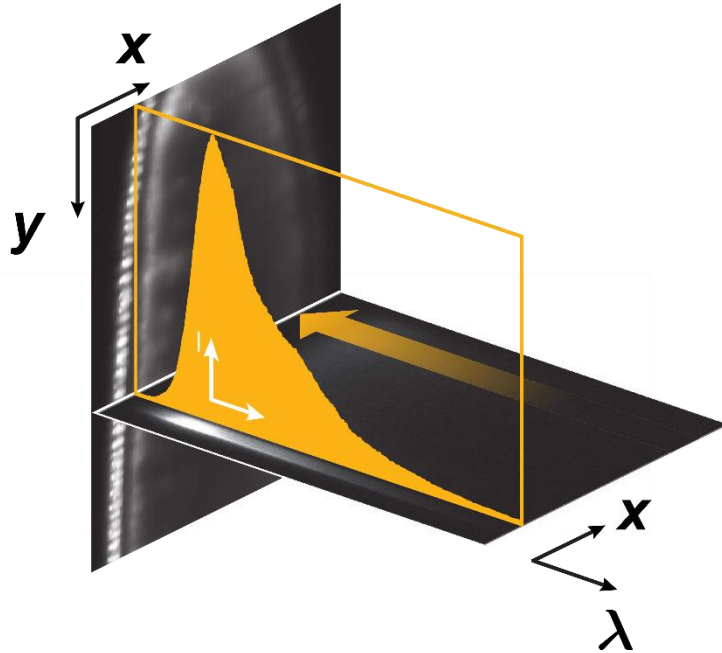
[Image adapted from [Wikimedia Commons](#)]

Fluorescence Microscopy usually based on Filters 4 / 21

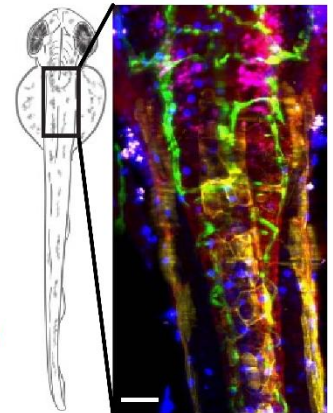
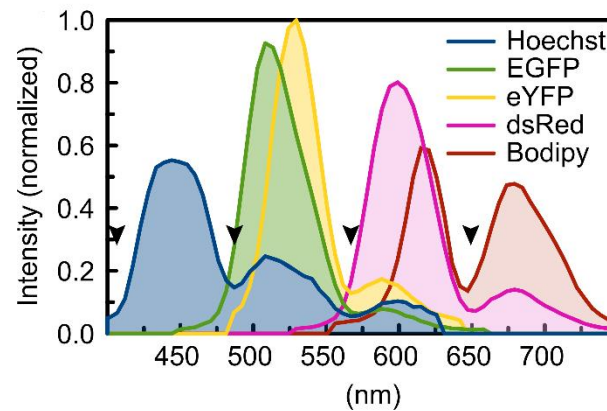


- ✓ Many photons are rejected
- ✓ Overlapping fluorophores cannot be separated
- ✓ Undesired fluorophores cannot be rejected

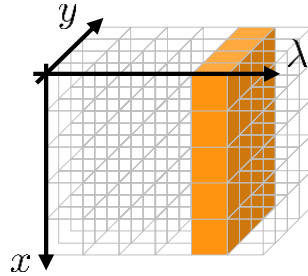




[W Jahr et al, *Nat. Commun.*, **6**, (2015)]

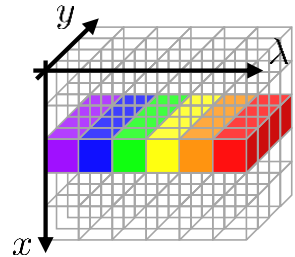


Optical filters



Challenge #1

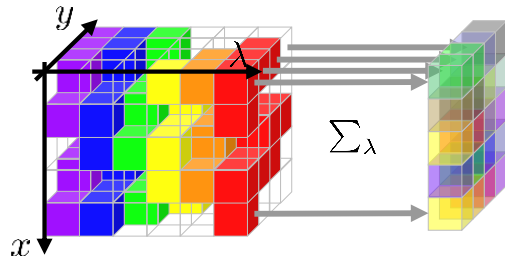
Resolution



Pushbroom

Challenge #2

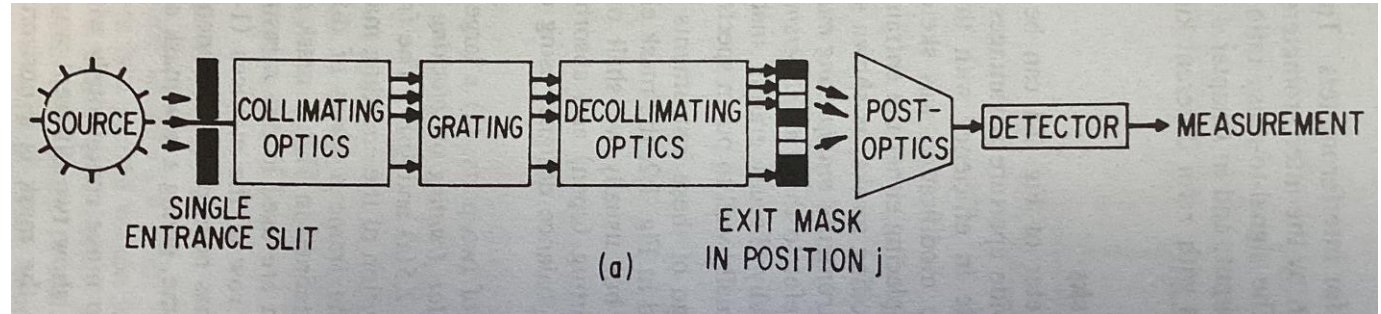
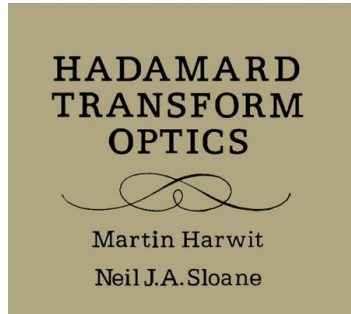
Speed



Computational

Challenge #3

Weak signals



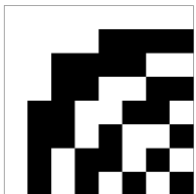
[M. Harwit and N Sloane, Academic Press, 1979]

'(...) conventional spectrometer is modified by using a mask to encode the light at the output'



Hadamard

$$m = Af$$
$$A \in \{-1, 1\}^{N \times N}$$



$$A^T A = N I_N$$

L2 minimization

$$f^* = \frac{1}{N} A m$$

Fellgett's advantage

$$\text{Hyp : } \text{var}(m_i) = \sigma^2, \forall i$$
$$\text{var}(f_i^*) = \frac{1}{N} \sigma^2 < \sigma^2$$



Improved SNRs

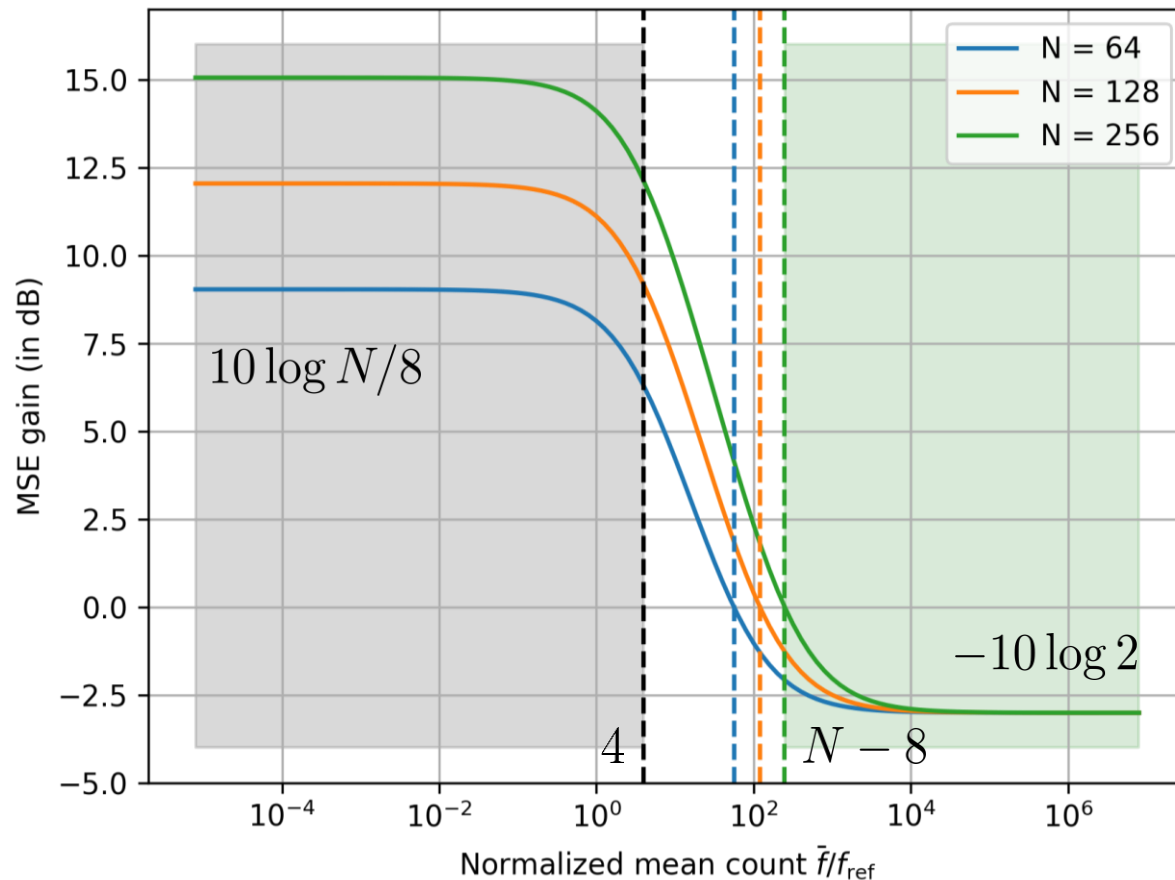
Poisson-Gaussian noise

$$\mathbf{m} \sim g\mathcal{P}(\mathbf{A}\mathbf{f}\Delta t) + \mathcal{N}(\mu_d, \sigma_d^2)$$

[EMVA
standard, 2021]

Fixed time budget

$$\Delta t = \frac{T}{2N}$$

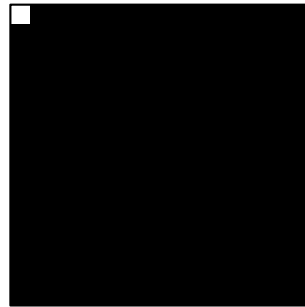


$$\bar{f} = \frac{1}{N} \sum_n f_n$$

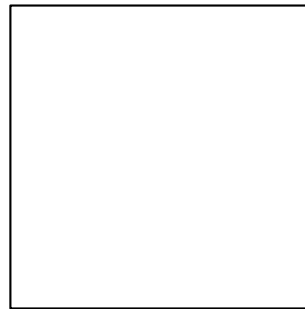
$$f_{\text{ref}} = \frac{\sigma_d^2}{g^2 T}$$



Raster scan



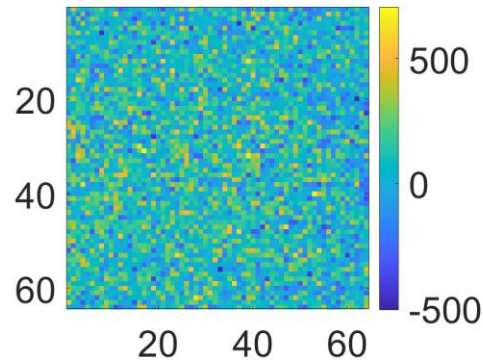
Hadamard scan



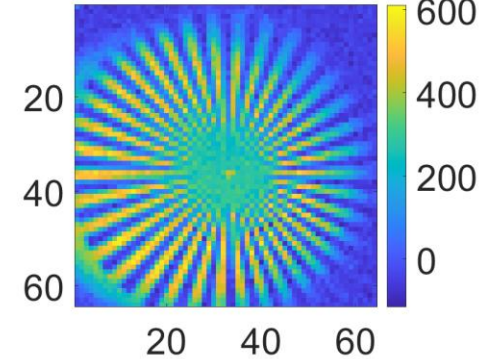
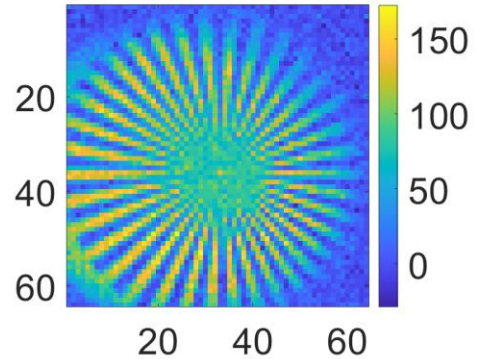
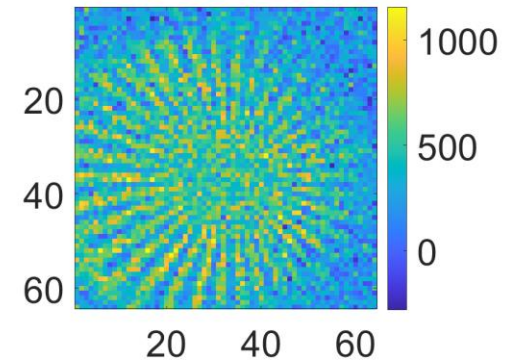
signal-to-noise ratio



signal x1

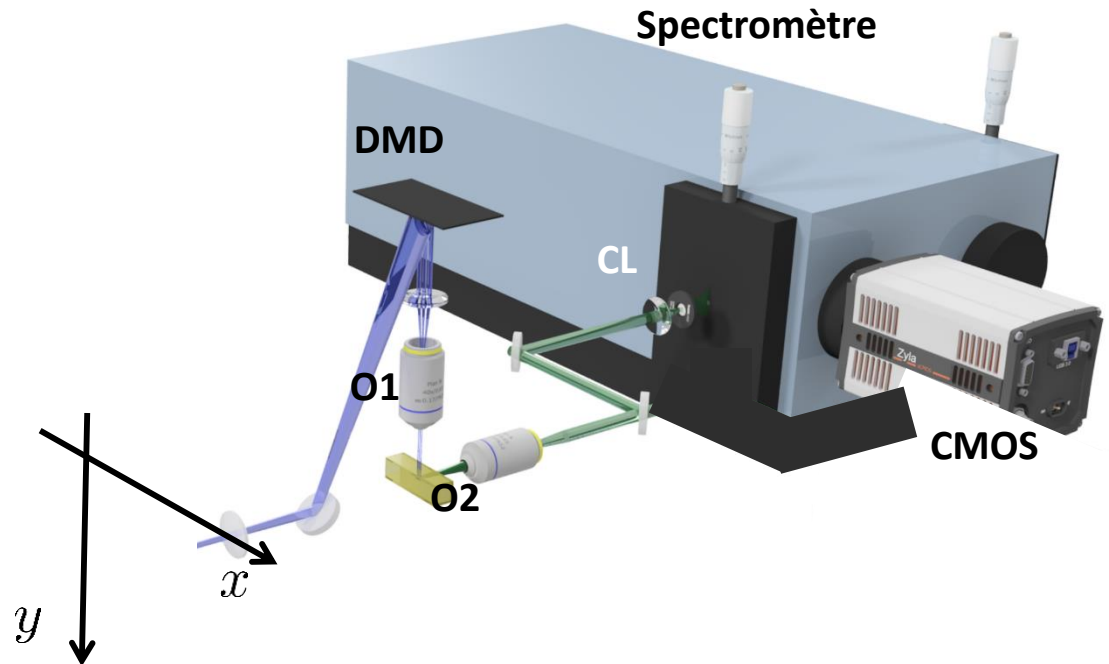
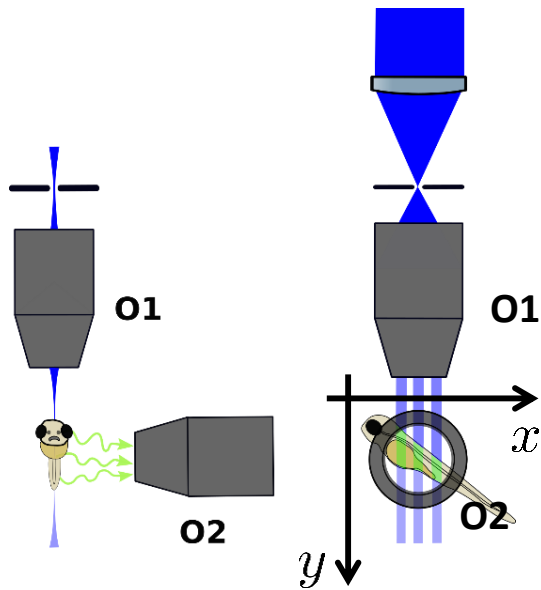


signal x4



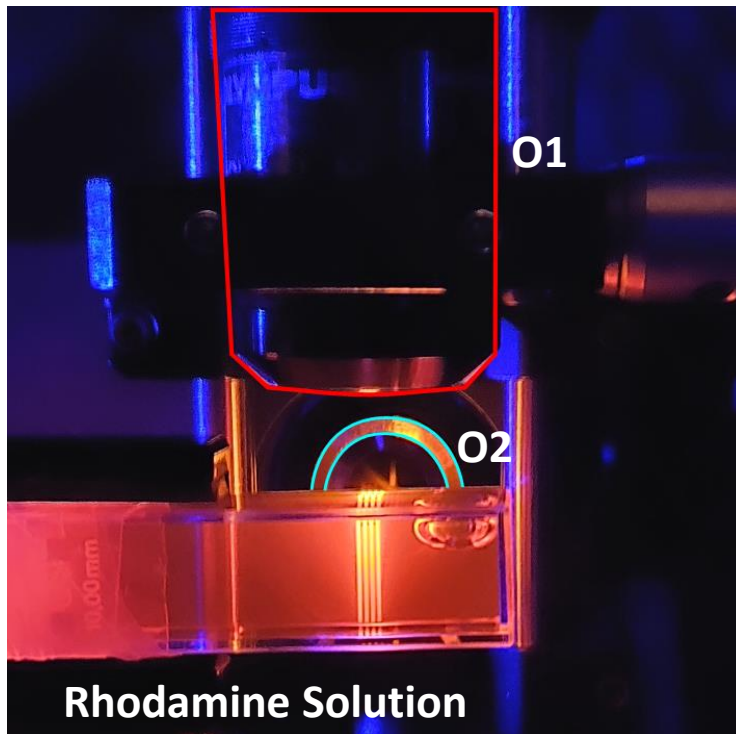
[N Ducros, 2020]

Proposed Method

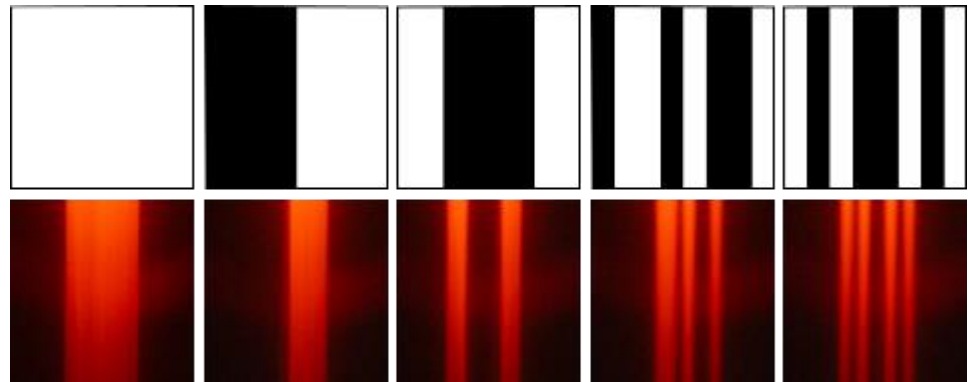


$$m_i(y, \lambda) = \int a_i(x) f(x, y, \lambda) dx, \quad 1 \leq i \leq M$$

[S. Crombez *et al.* Opt. Express **30**, 2022]



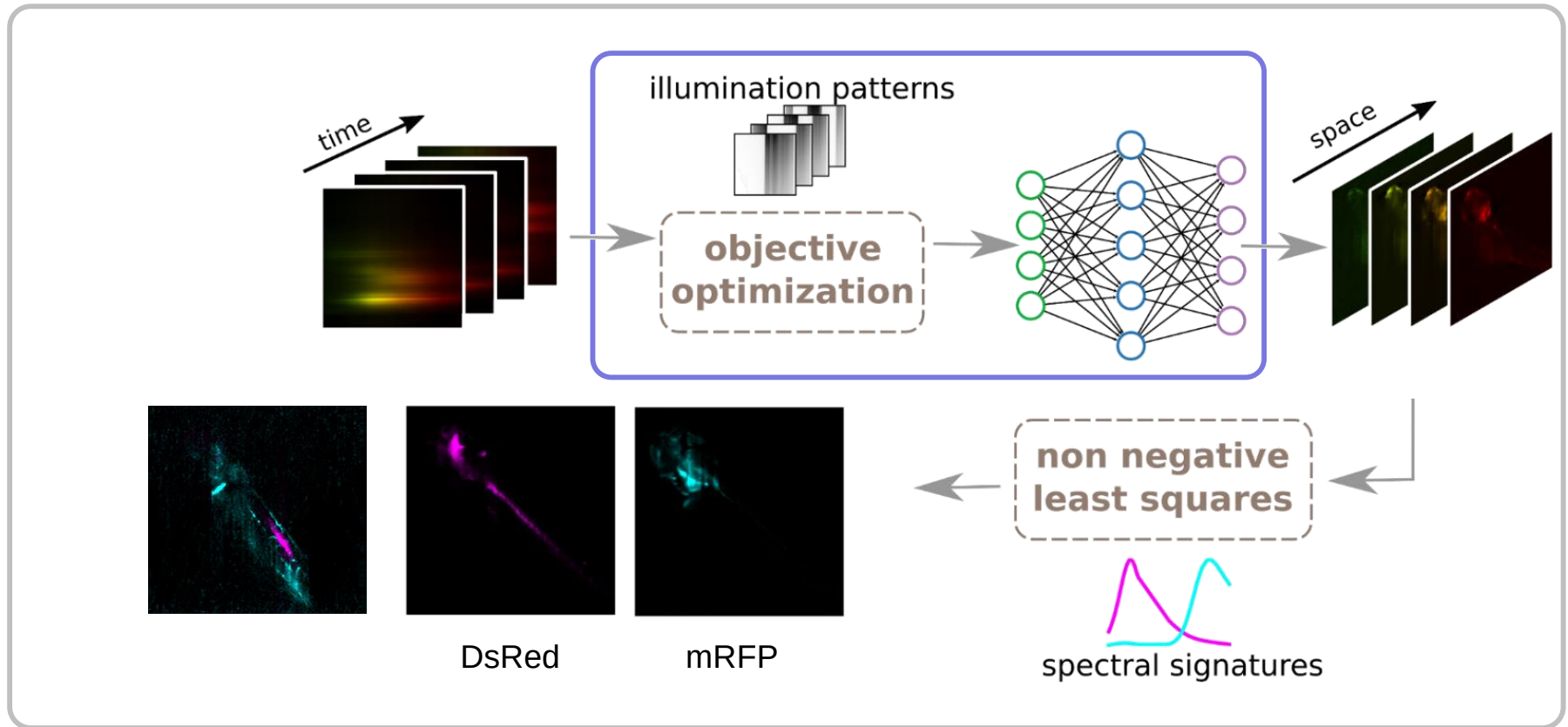
DMD (top) vs experimental (bottom) light patterns



- ✓ Light patterns need to be calibrated
- ✓ “Good” patterns (e.g., system matrix with low condition number) are highly desirable
- ✓ Spatial resolution: $\sim 60 \times 4 \mu\text{m}^2$

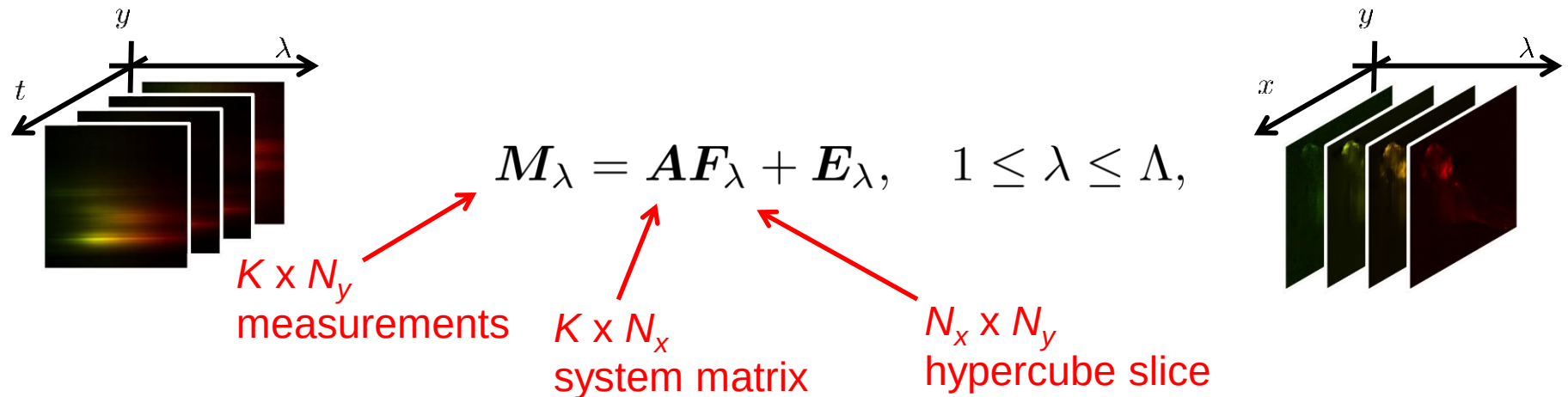
[S. Crombez *et al.* Opt. Express **30**, 2022]

Proof of principle



[S. Crombez *et al.*, preprint, 2024]

<https://hal.science/hal-04824372v1>



Slice-by-slice reconstruction

$$F_\lambda^* = \mathcal{R}_{\theta^*}(M_\lambda) \text{ for all } \lambda$$

End-to-end training / MMSE

$$\theta^* \in \arg \min_{\theta} \frac{1}{L} \sum_{\ell} \|\mathcal{R}_{\theta}(M^{\ell}) - F^{\ell}\|_{\text{F}}^2$$



Fast inference/small network
Training from grayscale image



No regularization/prior along the
spectral axis

Reconstruction challenges

- ✓ Varying noise levels
- ✓ Reconstruction time
- ✓ Avoid spectral distortions

Tikhonov (x-axis only) :

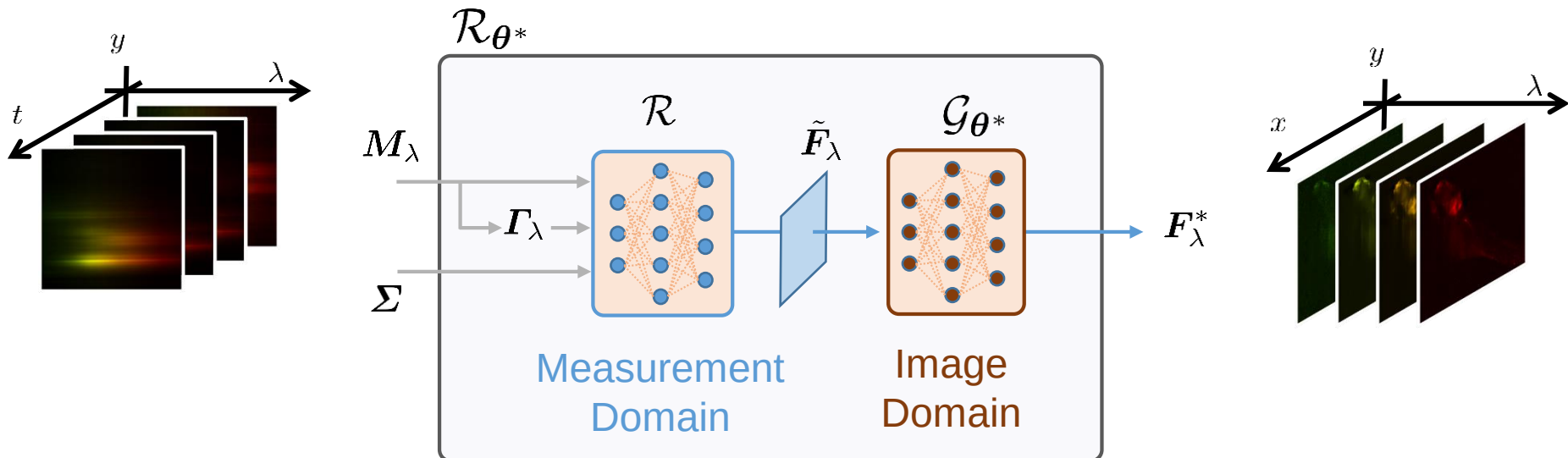
$$\mathcal{R}(M_\lambda) = \Sigma A^\top (A \Sigma A^\top + \Gamma_\lambda)^{-1} M_\lambda$$

Data-driven (x- and y-axis) :

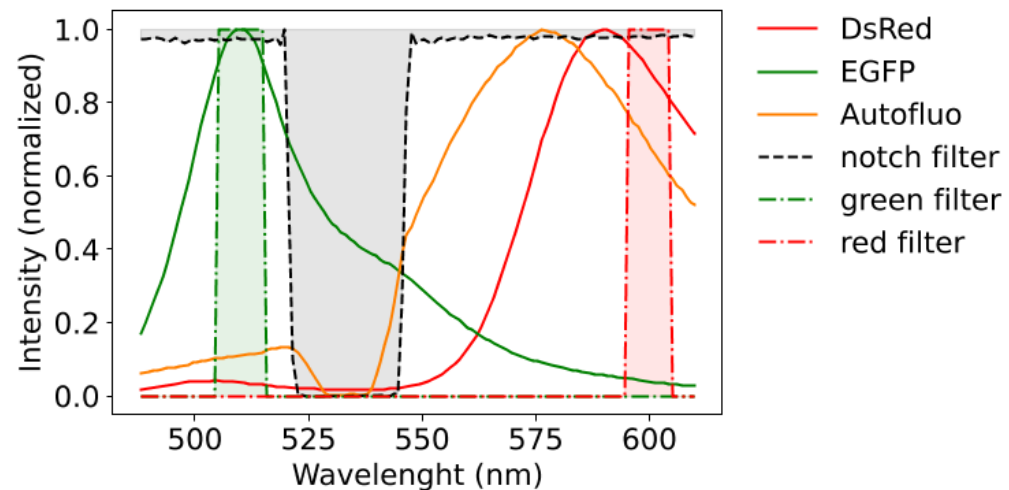
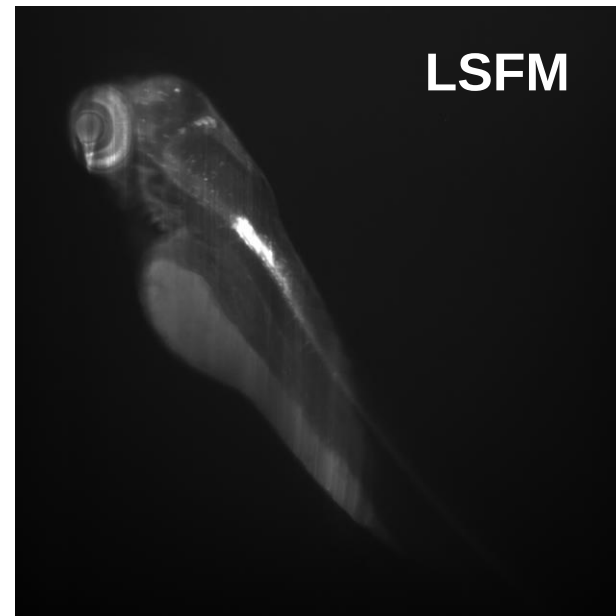
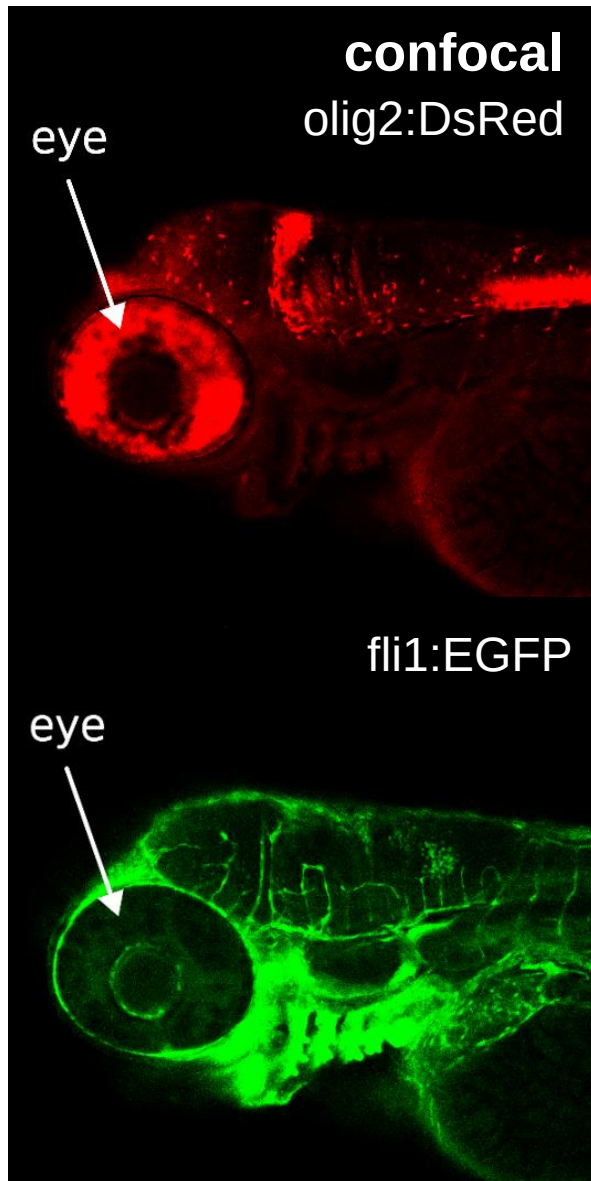
$$\mathcal{R}_{\theta^*}(M_\lambda) = (\mathcal{G}_{\theta^*} \circ \mathcal{R})(M_\lambda)$$

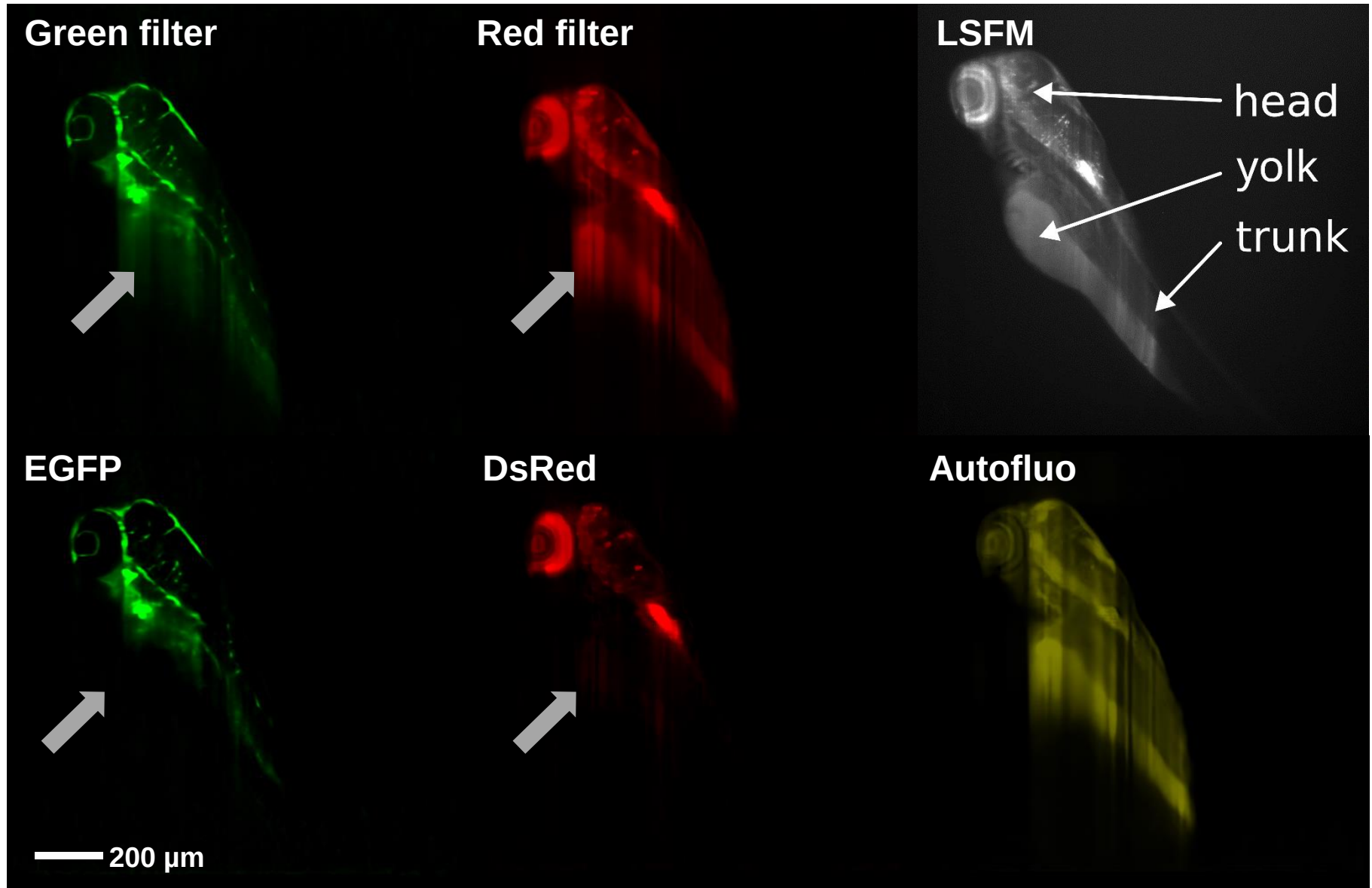
image profile
covariance

measurement
covariance



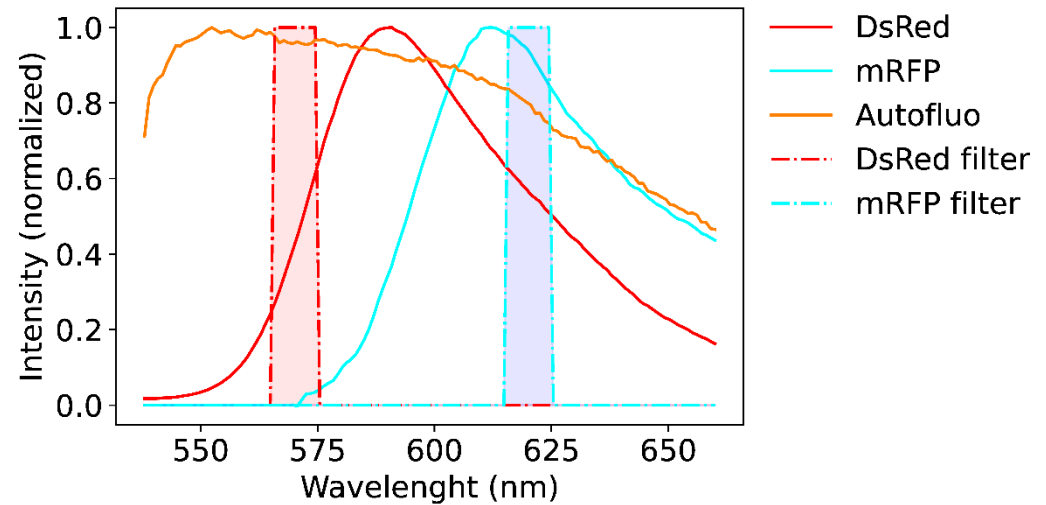
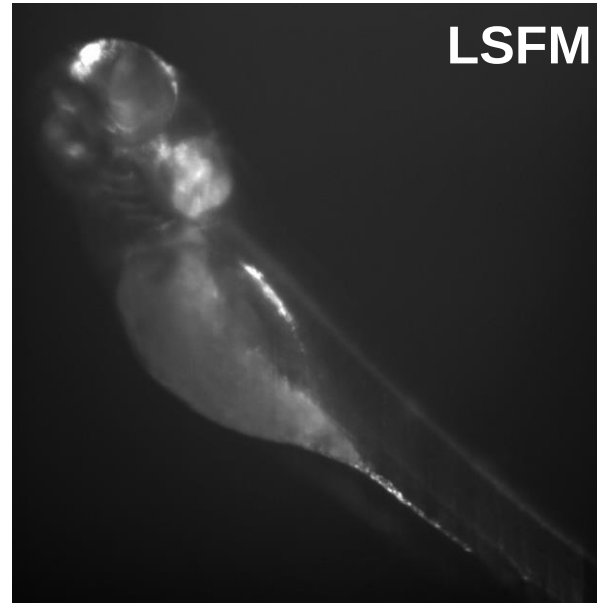
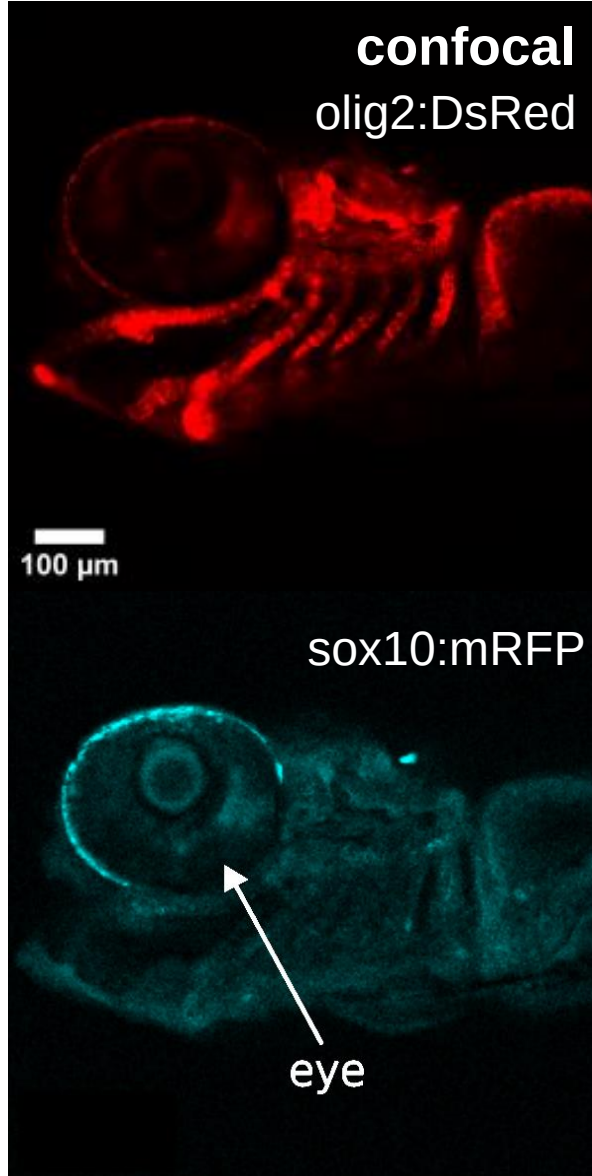
Results





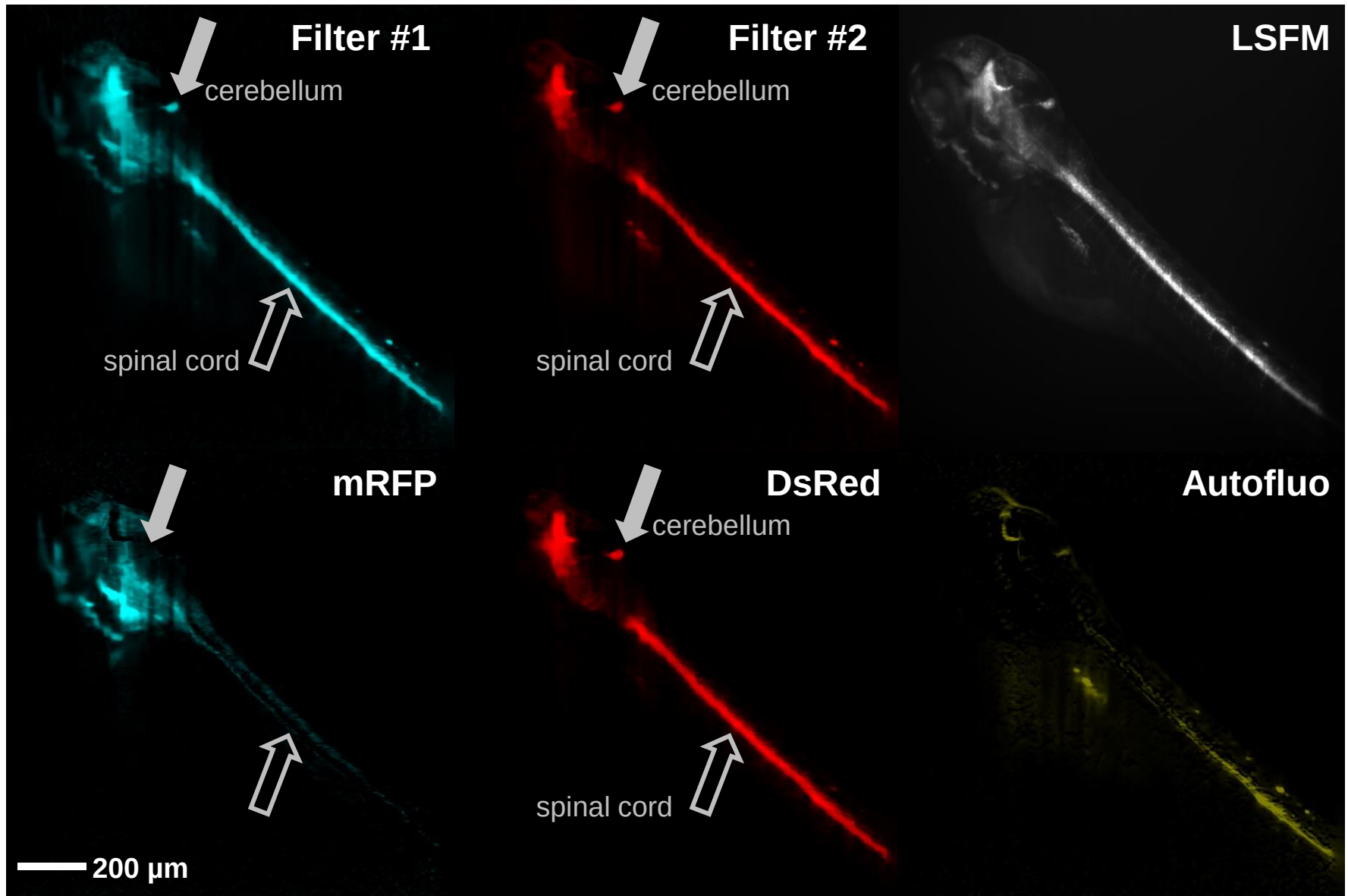
Sample #2: (sox10:mRFP;olig2:DsRed)

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Sample #2: (sox10:mRFP;olig2:DsRed)

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Limitations

LSFM

- Spatial resolution
~7 x 2 μm^2
- Acquisition speed
~8 min/slice

Passive imaging

- Extended FOV using experimental measurements
- Typical acquisition time is ~10 s

Future work (hardware)

LSFM

- Improved beam shaping along x-axis (~500 x 500 nm^2 ?)
- Z-axis beam shaping

Passive imaging

- x-axis only modulation

Future work (software)

- Reconstruct and unmix jointly [S. Hariga *et al.*, EUSIPCO, 2024]
- Data-driven (e.g., unrolled, PnP) for 3D spectral reconstruction
- 2-arm acquisition/data fusion
- Design of the patterns
- Etc.

Code (SPyRiT Python package): <https://spyrit.readthedocs.io/>

Data: <https://pilot-warehouse.creatis.insa-lyon.fr/>